

L Number	Hits	Search Text	DB	Time stamp
1	1589	inertial near2 sensor	USPAT	2004/04/15 17:18
2	56	((inertial near2 sensor) with pitch	USPAT	2004/04/15 17:18
3	9621	previous near2 position	USPAT	2004/04/15 17:19
4	31890	current near2 position	USPAT	2004/04/15 17:19
5	631	((previous near2 position) with (current near2 position)	USPAT	2004/04/15 17:19
6	0	((inertial near2 sensor) with pitch) same ((previous near2 position) with (current near2 position))	USPAT	2004/04/15 17:19
7	1	((inertial near2 sensor) with pitch) and ((previous near2 position) with (current near2 position))	USPAT	2004/04/15 17:20
8	6602	determin\$ near2 pitch	USPAT	2004/04/15 17:21
9	0	((determin\$ near2 pitch) same ((previous near2 position) with (current near2 position))	USPAT	2004/04/15 17:21
10	4	((determin\$ near2 pitch) and ((previous near2 position) with (current near2 position))	USPAT	2004/04/15 17:24
11	1576	calculat\$ near2 pitch	USPAT	2004/04/15 17:24
12	0	((calculat\$ near2 pitch) same ((previous near2 position) with (current near2 position))	USPAT	2004/04/15 17:24
13	5	((calculat\$ near2 pitch) and ((previous near2 position) with (current near2 position))	USPAT	2004/04/15 17:28
14	113	((previous near2 position) with (current near2 position)) and navigat\$	USPAT	2004/04/15 17:28
15	113	((previous near2 position) with (current near2 position)) and navigat\$	USPAT	2004/04/15 17:28
16	67	((previous near2 position) with (current near2 position)) and navigat\$ and vehicle	USPAT	2004/04/15 17:28
17	11	((previous near2 position) with (current near2 position)) and navigat\$ and vehicle) and pitch	USPAT	2004/04/15 17:28
18	3	((previous near2 position) with (current near2 position)) and navigat\$ and vehicle) and pitch) and (inertial near2 sensor)	USPAT	2004/04/15 17:28
19	11	((previous near2 position) with (current near2 position)) and navigat\$ and vehicle) and pitch	USPAT	2004/04/15 17:29
20	3	((previous near2 position) with (current near2 position)) and navigat\$ and vehicle) and pitch) and (inertial near2 sensor)	USPAT	2004/04/15 17:56
21	1164	pitch with (longitudinal and vertical)	USPAT	2004/04/15 17:56
22	8	((pitch with (longitudinal and vertical)) and GPS and navigat\$	USPAT	2004/04/15 17:58
23	1576	calculat\$ near2 pitch	USPAT	2004/04/15 17:58
24	11	((calculat\$ near2 pitch) same (longitudinal and vertical)	USPAT	2004/04/15 17:58
25	9	((calculat\$ near2 pitch) same (longitudinal and vertical)) and position	USPAT	2004/04/15 17:59